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## IN THE UNITED STATES PATENT & TRADEMARK OFFICE

## TITLE

FAULT TOLERANT STORAGE SYSTEM AND METHOD

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**BACKGROUND OF THE INVENTION** 

This application claims the benefit of U.S. Provisional Application No.

60/269,452, titled "A Method of Storing and Retrieving Information With Controllable

Redundancy for Fault Tolerance Distributed Data Storage" filed on February 16, 2001

for priority under 35 U.S.C. §119(e), is related thereto, is commonly assigned therewith,

and incorporates herein by reference in its entirety the subject matter thereof.

**Technical Field** 

This invention relates to the organization of a distributed data storage system, 10

more particularly, the present invention relates to the storage and retrieval of information

with controllable redundancy for fault tolerant distributed data storage.

Background

With the growth of the use of the Internet, the need for data storage systems with

the capability to manage huge amounts of information has grown dramatically. Such data

storage or information management systems must provide reliable service to millions of

computer users simultaneously.

In prior art data storage networks, a large amount of data is broken into smaller

pieces and transmitted using a store and forward mechanism.

Anyone deploying a data storage or information management system must deal

with insufficient communication channel bandwidth and the inability of computer

hardware components to handle the data storage load.

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One prior art approach to solving the problems of insufficient bandwidth and the inability of computer hardware to store sufficient amounts of data has been to build a

distributed network data storage system (Pfister 1998). In a typical distributed network

data storage system, data is stored on a network of computers which consists of a mesh of

data transmission links, switching nodes, and end nodes. The data pieces are transmitted

on a series of links which connect the source of the information and the actual destination

nodes for the stored information. The data pieces are then reassembled at the destination

node. The nodes along the path between the source of the information and its destination

are primarily responsible for making sure that each data piece received is transmitted on

the correct outgoing link so that the data properly reaches its destination.

To properly meet user demands for information, a distributed network data storage system must provide high-availability of stored data to the computers needing the

stored data (Pfister 1998). Specifically, a distributed network data storage system should

be able to stay on-line with consistent availability of uncorrupted data, even if some

hardware portion of the distributed network data storage system has crashed or becomes

inaccessible because of an inability to transmit data. This is shown in Figure 1, where

file pieces 3 and 5 have become inaccessible due to a hardware failure and a data

transmission line break, respectively.

To address the requirement for high-availability of stored data, one or more

variations of a data mirroring technique (U.S. Pat. No. 6,173,377, U.S. Pat. No.

6,157,991, U.S. Pat. No. 5,537,533) have been used in prior art data storage systems. In

the execution of a data mirroring technique, crucial data is simply duplicated in its

entirety at several locations in the distributed data storage system. Special care must be

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taken to keep the data consistent across all locations where it is stored (U.S. Pat. No.

5,537,533). However, full mirroring of all data is costly both in hardware and physical

time of transfer, particularly for large systems. One solution has been to keep the stored

data consistent across all nodes, especially when the stored data could be changed on-line

at several nodes simultaneously. This problem of keeping stored data consistent across

all nodes in a data storage network is far from trivial.

There is little doubt that providing high-availability features in a distributed data

storage system requires maintaining at least some level of redundancy of stored

information. Historically, the problems associated with redundant data storage were

addressed by the use of Redundant Arrays of Independent Disks (RAID) technology

(Pfister 1998, Patterson et al.). The main concept behind RAID data storage technology

is to divide the input data into units and then write/read several units of data

simultaneously to several hard disk data storage systems. Several of the most commonly

used configurations, or levels, of RAID arrays are described below.

The RAID Level 0 configuration implements a striped disk array for storing data.

In a RAID Level 0 configuration, the data is broken down into blocks and each block is

written to a separate data storage disk. The input/output performance of each disk drive

is greatly improved by spreading the input/output load across many channels and disk

drives. Reconstruction of the data set is accomplished by obtaining data blocks from

each separate data storage disk.

The best data storage performance is achieved when the data to be stored is

striped across multiple disk drives with each single disk drive attached to a single

controller. No parity calculation overhead is involved, and there are no fault tolerance

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capabilities in the RAID Level 0 configuration. There is no fault tolerance in the RAID

Level 0 configuration because a single disk drive is connected to a single controller.

Accordingly, the failure of just one disk drive will result in corruption of the stored data.

The RAID Level 1 configuration implements what is known as "disc mirroring."

Disc mirroring is done to assure the reliability of stored data and a high degree of fault

tolerance. A RAID Level 1 configuration also enhances data read performance, but the

improved data read performance and fault tolerance come at the expense of available

capacity in the disk drives used to store data. Specifically, the data to be stored is copied

and then stored on multiple disk drives (or "mirrored"). The storage of data on multiple

disk drives assures that, should one disk drive fail, the data is available from another disk

drive on which the same data has been stored. The data read performance gain of a

RAID Level 1 configuration can be realized if the redundant data is distributed evenly on

all of the disk drives of a mirrored set within the subsystem. In a RAID Level 1

configuration, the number of data read requests and total wait state times both drop

significantly. These drops are inversely proportional to the number of hard drives used in

a RAID Level 1 configuration.

A RAID Level 5 configuration data storage algorithm represents a data storage

methodology between a RAID Level 1 configuration and a RAID Level 0 configuration.

The RAID Level 5 configuration is the last of the most common RAID data storage

arrays in use, and is probably the most frequently implemented.

A RAID Level 5 configuration is really an adaptation of the RAID Level 0

configuration that sacrifices some data storage capacity for the same number of disk

drives. However, the RAID Level 5 configuration gains a high level of data integrity or

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fault tolerance. The RAID Level 5 configuration takes advantage of RAID Level 0's data

striping methods, except that data is striped with parity across all of the disk drives in the

array. The stripes of parity information are calculated using the "Exclusive OR" function.

By using the Exclusive OR function with a series of data stripes in the RAID Level 5

configuration, any lost data can easily be recovered. Should any one disk drive in the

array fail, the missing information can be determined in a manner similar to solving for a

single variable in an equation (for example, solving for x in the equation, 4 + x = 7). In

an Exclusive OR operation, the equation would be similar to 1 - x = 1. Thanks to the use

of the Exclusive OR operation, there is always only one possible solution (in this case, 0),

which provides a complete error recovery algorithm in a minimum amount of storage

space.

A RAID Level 5 configuration achieves very high data transfer performance by

reading data from or writing data to all of the disk drives simultaneously in parallel while

retaining the means to reconstruct data if a given disk drive fails, thus maintaining data

integrity for the data storage system.

A RAID Level 5 configuration minimizes the data write bottlenecks by

distributing parity stripes over a series of hard drives. In doing so, a RAID Level 5

configuration provides relief to the concentration of data write activity on a single disk

drive, in turn enhancing overall system performance.

The disadvantages of RAID-like implementation for distributed data storage

systems are clear. First, it is impossible to dynamically control redundancy (classic

RAID algorithms work in the case of failure of only one disk drive; if two or more disk

drives go off line simultaneously, there is no way to recover data). Second, RAID

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technology does not scale for more than ten disks, mainly due to the input/output

intensive fault-recovery procedures which make the RAID technology unsuitable for

systems where the unavailability of one or more nodes is common.

A similar data recovery problem arises when solving the problem of reliability of

information transmission via communication channels. In this case algorithms of the

Hamming error correction code (ECC) / error detection code (ECD) are usually used

(Roman 1996). In general, there are two approaches to solving the problem of reliability

of information transmission. Selecting a particular approach to solving this problem

usually depends on requirements associated with the information transmission process.

Both of the requirements associated with the information transmission process require

transmitting redundant information to recover data in case of error. The first approach,

called error-correction code (ECC), introduces redundancy into the stored information in

the form of extra bits transmitted together with a data block so that it is possible to

recover erroneous bits using received block and error-correction bits. The second

approach, called error-detection code ECD, differs from the first approach in that one can

only determine whether or not the data block contains errors without knowing which bits

are incorrect.

One major drawback of both the error correction code and error detection code

algorithms is that they are intended for data streaming recovery. Accordingly, these two

algorithms carry a significant overhead in performance and amount of redundancy data.

Even in case of errorless data transfer, one has to process a significantly larger amount of

data than is necessary. Also, these two algorithms rely on the probability of a channel

The first from their

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error. In other words, these two algorithms work correctly only if the total number of

errors in the received block of data does not exceed some predetermined number n.

Accordingly, there still remains a need in the art for a system which permits the

storage of large amounts of data across a distributed arbitrarily-connected network of

servers which provides high availability and fault tolerance.

**SUMMARY** 

The present invention defines a system and method for the storage of data across a

distributed arbitrarily-connected network of servers which provides high availability and

fault tolerance. More particularly, the disclosed system and method enables the storage

and retrieval of data with controllable redundancy. The controlled redundancy enables

the optimal utilization of data storage facilities. Using the disclosed data storage system,

it is possible to achieve an appropriate level of fault tolerance when either some of the

servers in a network become inaccessible because of internal malfunctions or their

connections to the data storage network are broken. According to the disclosed method

for data storage, data file storing is allowed without total mirroring of the stored data on

each server in the network.

Each complete set of data is broken into numbered, interchangeable data pieces of

equal size, the number of which "n" may vary over time. However, from any "k" (k\le n)

number of data pieces, it is always possible to restore the data storage file completely.

The use of this data storage system creates a condition of redundancy. The size of each

data piece is about 1/k of the size of the entire stored file. The total number "n" of file

pieces contained in a system may vary depending on the configuration of the arbitrary

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network of servers and on the number of computers contained therein. However, the

number of data pieces "n" is always equal to or greater than the number of data pieces

needed to restore a file. While changing the number "n", the data stored in the existing

pieces is not changed in any way. The number of data pieces may be large enough for

modern computer networks and defines the selection of the storage algorithms.

The disclosed system and method for the storage of data across a distributed

arbitrarily-connected network of servers also could be used for significant (up to "k"

times) enlargement of the data transfer rate because of the fact that all pieces of the stored

file could be transferred from "k" servers in parallel and independently from each other.

Under some conditions, the disclosed data storage system and method provides the

optimal utilization of network bandwidth and increases the rate of overall file transfer.

BRIEF DESCRIPTION OF THE DRAWING FIGURES

A better understanding of the data storage system and method of the

present invention may be had by reference to the drawing figures wherein:

FIG. 1 is a schematic of a prior art system and method for information access on a

distributed arbitrarily-connected network of servers showing the effect of a broken server

or a break in a transmission line;

FIG. 2 is a schematic showing the system and method of the present invention for

disassembling a file and storing file pieces on a distributed arbitrarily-connected network

of servers:

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FIG. 3 is a schematic showing the system and method of the present invention for

file restoration; specifically, the collection of file pieces from the distributed

arbitrarily-connected network of servers and their assemblage into the original file; and

FIG. 4 is a schematic showing the system and method of the present invention for

additional generation of file pieces which could be done after initial distribution of data

across the distributed arbitrarily-connected network of servers.

DETAILED DESCRIPTION OF THE INVENTION

The present invention defines a system and method for the storage of data files

across a distributed arbitrarily-connected network of servers. Using the disclosed system

and method, it is possible to achieve an appropriate level of data storage fault tolerance in

a situation when some network servers become inaccessible because of internal

malfunctions or breaks in the connection between servers in the network. The present

invention provides a system and method which allows the storage of data files without a

total mirroring of all data stored on each server in the network.

Each data file is proposed to be stored as a set of data pieces whose number "n"

may vary over time. However, from any "k" number  $(k \le n)$  of data pieces of the stored

data file, it is always possible to restore the entire data file completely. The use of this

data storage system creates a condition of redundancy. The size of each piece of the

stored data file is about 1/k of the size of the entire stored data file. The number "n" of

data pieces contained in the data storage system may vary depending on the configuration

of the arbitrary network of servers and on the number of servers in the network. While

changing the number "n", the data stored in the existing pieces is not changed in any way.

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The first step in the disclosed method is to define an appropriate amount of data pieces P<sub>1</sub>, P<sub>2</sub>, P<sub>3</sub> ... P<sub>n</sub>. A minimal amount "k" of data pieces needed to completely restore the file is defined usually from size requirements (for example, the size of one file piece could be taken close to optimal for transfer via Internet TCP/IP about 1 K byte).

The next step in the disclosed method is to define a fault tolerance level. For example, in a distributed arbitrarily-connected network including some number "L" working servers, fault tolerance is determined by setting the number "M" (M<L) of the working servers that could be switched off (or fail by themselves or due to network inaccessibility) simultaneously at any moment in time. To reconstruct the original file, at least M+k data pieces of the original file must be created and stored on at least M+k separate servers in the network. In such a case, the ability to restore the original file, even in case of the simultaneous unavailability of M servers, is guaranteed. This is because if M servers become unavailable, the required minimum number of data pieces to reconstruct the data set will still be available ((M+k) - M = k).

In Fig. 2 the process of file storing inside a distributed data storage system is shown. The first data file is split into at least M+k pieces as shown in Figure 2 by the blocks labeled P<sub>1</sub>, P<sub>2</sub>, P<sub>3</sub> ... P<sub>n</sub>. In the second step, all of the created pieces are placed on different servers 1, 2, 3, 4 ... n in the distributed arbitrarily-connected network of servers 100. Only after completion of such an operation will the step of storing the entire data file be treated as complete.

In Fig. 3 the process of retrieving the stored data from a distributed arbitrarily-connected data storage network 100 is shown. In the first stage of data retrieval, the required minimum number of data pieces "k" are received from the servers

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1, 2, 3, 4...n on which the data pieces are stored. However, because not all servers are

needed to obtain "k" data pieces, some of the servers, e.g., server 4 in Fig. 3, could be

inaccessible because of internal failure or because of data transmission line problems.

Because at least "k" servers are still available within network 100, the entire data file can

still be reconstructed. Therefore, in the first stage of data retrieval, as shown in the left

side of Fig. 3, "k" data pieces would be collected, and in the second stage of data

retrieval, as shown in the right side of Figure 3, the collected pieces are reconstructed into

the original file on the client computer 200.

In Fig. 4 the process of the additional generation of data pieces done after the

initial distribution of data across a distributed arbitrarily-connected network 100 of

servers 1, 2, 3, 4...n is shown.

During the normal operation of the disclosed network storage system, the

requested amount of file pieces "n" could vary. For example, some servers could be

permanently shut down or the requested level of fault tolerance increases. In such cases,

additional data pieces must be created; that is, the number "n" must increase. To create

an additional set of data pieces, as shown in the central portion of Fig. 4, an original file

is assembled following the standard procedure for splitting the stored data file into pieces

as shown in Fig. 2. Later, additional data pieces are generated 300 and distributed across

a data storage network 400 on non-used servers. The amount of redundancy is increased

by a quantum of 1/k of the original file size.

The disclosed method also could be used for a significant (up to "k" times)

increase in data transfer rate because pieces of a data storage file could be transferred in

parallel from "k" or more servers independently from each other. Under some conditions,

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this method could give the optimal utilization of network bandwidth and speed up overall

file transfer time.

While the disclosed invention has been described in terms of its preferred

embodiment, those of ordinary skill in the art will understand that numerous other

embodiments have been enabled. Such other embodiments shall be included within the

scope and meaning of the appended claims.